## M74HC4538

## DUAL RETRIGGERABLE MONOSTABLE MULTIVIBRATOR

- HIGH SPEED :
$\mathrm{t}_{\mathrm{PD}}=25 \mathrm{~ns}$ (TYP.) at $\mathrm{V}_{\mathrm{CC}}=6 \mathrm{~V}$
- LOW POWER DISSIPATION:

STAND BY STATE :
$\mathrm{I}_{\mathrm{CC}}=4 \mu \mathrm{~A}$ (MAX.) at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$
ACTIVE STATE :
$\mathrm{I}_{\mathrm{CC}}=200 \mu \mathrm{~A}$ (TYP.) at $\mathrm{V}_{\mathrm{CC}}=6 \mathrm{~V}$

- HIGH NOISE IMMUNITY:
$\mathrm{V}_{\mathrm{NIH}}=\mathrm{V}_{\mathrm{NIL}}=28 \% \mathrm{~V}_{\mathrm{CC}}(\mathrm{MIN}$.
- SYMMETRICAL OUTPUT IMPEDANCE:
$\left|\mathrm{I}_{\mathrm{OH}}\right|=\mathrm{I}_{\mathrm{OL}}=4 \mathrm{~mA}(\mathrm{MIN})$
- BALANCED PROPAGATION DELAYS: $\mathrm{t}_{\mathrm{PLH}} \cong \mathrm{t}_{\mathrm{PHL}}$
- WIDE OPERATING VOLTAGE RANGE: $\mathrm{V}_{\mathrm{CC}}(\mathrm{OPR})=2 \mathrm{~V}$ to 6 V
- WIDE OUTPUT PULSE WIDTH RANGE :
$\mathrm{t}_{\text {WOUT }}=120 \mathrm{~ns} \sim 60 \mathrm{~s}$ OVER AT $\mathrm{V}_{\mathrm{CC}}=4.5 \mathrm{~V}$
- PIN AND FUNCTION COMPATIBLE WITH 74 SERIES 4538


## DESCRIPTION

The M74HC4538 is an high speed CMOS MONOSTABLE MULTIVIBRATOR fabricated with silicon gate $\mathrm{C}^{2} \mathrm{MOS}$ technology.
Each multivibrator features both a negative A, and a positive B, edge triggered input, either of which can be used as an inhibit input. Also included is a clear input that when taken low resets the one shot. The monostable multivibrator are


ORDER CODES

| PACKAGE | TUBE | T \& R |
| :---: | :---: | :---: |
| DIP | M74HC4538B1R |  |
| SOP | M74HC4538M1R | M74HC4538RM13TR |
| TSSOP |  | M74HC4538TTR |

retriggerable. That is, they may be triggered repeatedly while their outputs are generating a pulse and the pulse will be extended. Pulse width stability over a wide range of temperature and supply is achieved using linear CMOS techniques.
The output pulse equation is simply :
$P W=0.7(R)(C)$ where $P W$ is in seconds, $R$ in Omhs and $C$ is in Farads.
All inputs are equipped with protection circuits against static discharge and transient excess voltage.

## PIN CONNECTION AND IEC LOGIC SYMBOLS



INPUT AND OUTPUT EQUIVALENT CIRCUIT


PIN DESCRIPTION

| PIN No | SYMBOL | NAME AND FUNCTION |
| :---: | :---: | :--- |
| 1,15 | $1 \mathrm{~T} 1,2 \mathrm{~T} 1$ | External Capacitor Con- <br> nections |
| 2,14 | $1 \mathrm{~T} 2,2 \mathrm{~T} 2$ | External Resistor/ <br> Capacitor Connections |
| 3,13 | $\overline{1 \mathrm{CD}}, \overline{2 \mathrm{CD}}$ | Direct Reset Inputs <br> (Active Low) |
| 4,12 | $1 \mathrm{~A}, 2 \mathrm{~A}$ | Trigger Inputs (LOW to <br> HIGH, Edge-Triggered) |
| 5,11 | $1 \overline{\mathrm{~B}}, 2 \overline{\mathrm{~B}}$ | Trigger Inputs (HIGH to <br> LOW, Edge Triggered) |
| 6,10 | Q 1, Q2 | Pulse Outputs |
| 7,9 | $\overline{\mathrm{Q} 1, \overline{\mathrm{Q} 2}}$ | Complementary Pulse <br> Outputs |
| 8 | GND | Ground (0V) |
| 16 | Vcc | Positive Supply Voltage |

TRUTH TABLE

| INPUTS |  |  | OUTPUTS |  | NOTE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{A}$ | $\overline{\mathbf{B}}$ | $\overline{\mathbf{C D}}$ | $\mathbf{Q}$ | $\overline{\mathbf{Q}}$ |  |
| $\Gamma$ | H | H | $\breve{\mathrm{Q}}$ | $\boxed{ }-$ | OUTPUT ENABLE |
| X | L | H | L | H | INHIBIT |
| H | X | H | L | H | INHIBIT |
| L | L | H | $\boxed{\mathrm{L}}$ | L | OUTPUT ENABLE |
| X | X | L | L | H | INHIBIT |
| X: Don't Care |  |  |  |  |  |

## SYSTEM DIAGRAM



This logic diagram has not be used to estimate propagation delays

TIMING CHART


## BLOCK DIAGRAM



[^0]
## FUNCTIONAL DESCRIPTION

STAND-BY STATE
The external capacitor,Cx, is fully charged to Vcc in the stand-by state. Hence, before triggering, transistor Qp and Qn (connected to the Rx/Cx node) are both turned-off. The two comparators that control the timing and the two reference voltage sources stop operating. The total supply current is therefore only leakage current.

## TRIGGER OPERATION

Triggering occurs when :
1 st) $A$ is "LOW" and $\bar{B}$ has a falling edge;
2 nd) $\bar{B}$ is "HIGH" and $A$ has a rising edge;
After the multivibrator has been retriggered comparator C1 and C2 start operating and Qn is turned on. Cx then discharges through Qn. The voltage at the node Rx/Cx external falls.
When it reaches $\mathrm{V}_{\text {REFL }}$ the output of comparator C1 becomes low. This in turn reset the flip-flop and Qn is turned off.
At this point C 1 stops functioning but C 2 continues to operate.
The voltage at R/C external begins to rise with a time constant set by the external components Rx , Cx.

Triggering the multivibrator causes $Q$ to go high after internal delay due to the flip-flop and the gate. $Q$ remains high until the voltage at $R / C$ external rises again to $\mathrm{V}_{\text {REFH }}$. At this point C 2 output goes low and $G$ goes low. C2 stop
operating. That means that after triggering when the voltage R/C external returns to $\mathrm{V}_{\text {REFH }}$ the multivibrator has returned to its MONOSTABLE STATE. In the case where Rx . Cx are large enough and the discharge time of the capacitor and the delay time in the I.C. can be ignored, the width of the output pulse tw (out) is as follows:

$$
\mathrm{t}_{\mathrm{W}(\mathrm{OUT})}=0.72 \mathrm{Cx} \cdot \mathrm{Rx}
$$

## RE - TRIGGERED OPERATION

When a second triggere pulse follows the first its effect will depend on the state of the multivibrator. If the capacitor Cx is being charged the voltage level of Rx/Cx external falls to $V_{\text {REFL }}$ again and $Q$ remains High i.e. the retrigger pulse arrives in a time shorter than the period $R x$. Cx seconds, the capacitor charging time constant. If the second trigger pulse is very close to the initial trigger pulse it is ineffective ; i.e. the second trigger must arrive in the capacitor discharge cycle to be ineffective; Hence the minimum time for a second trigger to be effective, trr (MIN.) depends on Vcc and Cx

## RESET OPERATION

$\overline{\mathrm{CD}}$ is normally high. If $\overline{\mathrm{CD}}$ is low, the trigger is not effective because Q output goes low and trigger control flip-flop is reset.
Also transistor Op is turned on and Cx is charged quickly to Vcc. This means if $\overline{\mathrm{CD}}$ input goes low the IC becomes waiting state both in operating and non operating state.

## ABSOLUTE MAXIMUM RATINGS

| Symbol | Parameter | Value | Unit |
| :---: | :--- | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply Voltage | -0.5 to +7 | V |
| $\mathrm{~V}_{\mathrm{I}}$ | DC Input Voltage | -0.5 to $\mathrm{V}_{\mathrm{CC}}+0.5$ | V |
| $\mathrm{~V}_{\mathrm{O}}$ | DC Output Voltage | -0.5 to $\mathrm{V}_{\mathrm{CC}}+0.5$ | V |
| $\mathrm{I}_{\mathrm{IK}}$ | DC Input Diode Current | $\pm 20$ | mA |
| $\mathrm{I}_{\mathrm{OK}}$ | DC Output Diode Current | $\pm 20$ | mA |
| $\mathrm{I}_{\mathrm{O}}$ | DC Output Current | $\pm 25$ | mA |
| $\mathrm{I}_{\mathrm{CC}}$ or $\mathrm{I}_{\mathrm{GND}}$ | DC $\mathrm{V}_{\mathrm{CC}}$ or Ground Current | $\pm 50$ | mA |
| $\mathrm{P}_{\mathrm{D}}$ | Power Dissipation | $500\left(^{*}\right)$ | mW |
| $\mathrm{T}_{\text {stg }}$ | Storage Temperature | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{L}}$ | Lead Temperature (10 sec) | 300 | ${ }^{\circ} \mathrm{C}$ |

[^1]RECOMMENDED OPERATING CONDITIONS

| Symbol | Parameter |  | Value | Unit |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply Voltage |  | 2 to 6 | V |
| $V_{1}$ | Input Voltage |  | 0 to $\mathrm{V}_{\mathrm{CC}}$ | V |
| $\mathrm{V}_{\mathrm{O}}$ | Output Voltage |  | 0 to $\mathrm{V}_{\mathrm{CC}}$ | V |
| $\mathrm{T}_{\text {op }}$ | Operating Temperature |  | -55 to 125 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{t}_{\mathrm{r}}, \mathrm{t}_{\mathrm{f}}$ | Input Rise and Fall Time ( $\overline{\mathrm{CD}}$ only) | $\mathrm{V}_{\mathrm{CC}}=2.0 \mathrm{~V}$ | 0 to 1000 | ns |
|  |  | $\mathrm{V}_{\mathrm{CC}}=4.5 \mathrm{~V}$ | 0 to 500 | ns |
|  |  | $\mathrm{V}_{\mathrm{CC}}=6.0 \mathrm{~V}$ | 0 to 400 | ns |
| Cx | External Capacitor |  | NO LIMITATION | pF |
| Rx | External Resistor | Vcc < 3V | 5 K to 1M | $\Omega$ |
|  |  | $\mathrm{Vcc} \geq 3 \mathrm{~V}$ | 1 K to 1M |  |

The Maximum allowable values of Cx and Rx are a function of leakage of capacitor Cx , the leakage of device and leakage due to the board layout and surface resistance. Susceptibility to externally induced noise may occur for $\mathrm{Rx}>1 \mathrm{M} \Omega$

DC SPECIFICATIONS

| Symbol | Parameter | Test Condition |  | Value |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{aligned} & \mathrm{V}_{\mathrm{Cc}} \\ & (\mathrm{~V}) \end{aligned}$ |  | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | -40 to $85^{\circ} \mathrm{C}$ |  | -55 to $125^{\circ} \mathrm{C}$ |  |  |
|  |  |  |  | Min. | Typ. | Max. | Min. | Max. | Min. | Max. |  |
| $\mathrm{V}_{\mathrm{IH}}$ | High Level Input Voltage | 2.0 |  | 1.5 |  |  | 1.5 |  | 1.5 |  | V |
|  |  | 4.5 |  | 3.15 |  |  | 3.15 |  | 3.15 |  |  |
|  |  | 6.0 |  | 4.2 |  |  | 4.2 |  | 4.2 |  |  |
| $\mathrm{V}_{\text {IL }}$ | Low Level Input Voltage | 2.0 |  |  |  | 0.5 |  | 0.5 |  | 0.5 | V |
|  |  | 4.5 |  |  |  | 1.35 |  | 1.35 |  | 1.35 |  |
|  |  | 6.0 |  |  |  | 1.8 |  | 1.8 |  | 1.8 |  |
| $\mathrm{V}_{\mathrm{OH}}$ | High Level Output Voltage | 2.0 | $\mathrm{I}_{\mathrm{O}}=-20 \mu \mathrm{~A}$ | 1.9 | 2.0 |  | 1.9 |  | 1.9 |  | V |
|  |  | 4.5 | $\mathrm{I}_{\mathrm{O}}=-20 \mu \mathrm{~A}$ | 4.4 | 4.5 |  | 4.4 |  | 4.4 |  |  |
|  |  | 6.0 | $\mathrm{I}_{\mathrm{O}}=-20 \mu \mathrm{~A}$ | 5.9 | 6.0 |  | 5.9 |  | 5.9 |  |  |
|  |  | 4.5 | $\mathrm{I}_{\mathrm{O}}=-4.0 \mathrm{~mA}$ | 4.18 | 4.31 |  | 4.13 |  | 4.10 |  |  |
|  |  | 6.0 | $\mathrm{I}_{\mathrm{O}}=-5.2 \mathrm{~mA}$ | 5.68 | 5.8 |  | 5.63 |  | 5.60 |  |  |
| $\mathrm{V}_{\text {OL }}$ | Low Level Output Voltage | 2.0 | $\mathrm{I}_{\mathrm{O}}=20 \mu \mathrm{~A}$ |  | 0.0 | 0.1 |  | 0.1 |  | 0.1 | V |
|  |  | 4.5 | $\mathrm{I}_{\mathrm{O}}=20 \mu \mathrm{~A}$ |  | 0.0 | 0.1 |  | 0.1 |  | 0.1 |  |
|  |  | 6.0 | $\mathrm{I}_{\mathrm{O}}=20 \mu \mathrm{~A}$ |  | 0.0 | 0.1 |  | 0.1 |  | 0.1 |  |
|  |  | 4.5 | $\mathrm{I}_{\mathrm{O}}=4.0 \mathrm{~mA}$ |  | 0.17 | 0.26 |  | 0.33 |  | 0.40 |  |
|  |  | 6.0 | $\mathrm{I}_{\mathrm{O}}=5.2 \mathrm{~mA}$ |  | 0.18 | 0.26 |  | 0.33 |  | 0.40 |  |
| 1 | Input Leakage Current | 6.0 | $\mathrm{V}_{1}=\mathrm{V}_{\text {CC }}$ or GND |  |  | $\pm 0.1$ |  | $\pm 1$ |  | $\pm 1$ | $\mu \mathrm{A}$ |
| I | Input Leakage Current | 6.0 | $\begin{gathered} \mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}} \text { or GND } \\ \text { Rext/Cext } \end{gathered}$ |  |  | $\pm 0.1$ |  | $\pm 1$ |  | $\pm 1$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{CC}}$ | Quiescent Supply Current | 6.0 | $\mathrm{V}_{1}=\mathrm{V}_{\text {CC }}$ or GND |  |  | 4 |  | 40 |  | 80 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{CC}}$ | Quiescent Supply Current | 2.0 | $\begin{gathered} \mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}} \text { or } \mathrm{GND} \\ \text { Pin } 2 \text { or } 14 \\ \mathrm{~V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{CC}} / 2 \end{gathered}$ |  | 40 | 120 |  | 160 |  | 200 | $\mu \mathrm{A}$ |
|  |  | 4.5 |  |  | 0.2 | 0.3 |  | 0.4 |  | 0.6 | mA |
|  |  | 6.0 |  |  | 0.3 | 0.6 |  | 0.8 |  | 1.0 | mA |

M74HC4538

AC ELECTRICAL CHARACTERISTICS ( $\mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$, Input $\mathrm{t}_{\mathrm{r}}=\mathrm{t}_{\mathrm{f}}=6 \mathrm{~ns}$ )

| Symbol | Parameter | Test Condition |  |  | Value |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathrm{V}_{\mathrm{Cc}}$ <br> (V) |  |  | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | -40 to $85^{\circ} \mathrm{C}$ |  | -55 to $125^{\circ} \mathrm{C}$ |  |  |
|  |  |  |  |  | Min. | Typ. | Max. | Min. | Max. | Min. | Max. |  |
| ${ }_{\text {t }}^{\text {LLH }}{ }^{\text {t }}$ THL | Output Transition Time | 2.0 |  |  |  | 30 | 75 |  | 95 |  | 110 | ns |
|  |  | 4.5 |  |  |  | 8 | 15 |  | 19 |  | 22 |  |
|  |  | 6.0 |  |  |  | 7 | 13 |  | 16 |  | 19 |  |
| $\mathrm{t}_{\text {PLH }} \mathrm{t}_{\text {PHL }}$ | Propagation Delay Time <br> ( $\mathrm{A}, \overline{\mathrm{B}}-\mathrm{Q}, \overline{\mathrm{Q}}$ ) | 2.0 |  |  |  | 120 | 250 |  | 315 |  | 375 | ns |
|  |  | 4.5 |  |  |  | 30 | 50 |  | 63 |  | 75 |  |
|  |  | 6.0 |  |  |  | 25 | 43 |  | 54 |  | 64 |  |
| $\mathrm{t}_{\text {PLH }} \mathrm{t}_{\text {PHL }}$ | Propagation Delay Time$(\overline{C D}-Q, \bar{Q})$ | 2.0 |  |  |  | 100 | 195 |  | 245 |  | 295 | ns |
|  |  | 4.5 |  |  |  | 25 | 39 |  | 49 |  | 59 |  |
|  |  | 6.0 |  |  |  | 20 | 33 |  | 42 |  | 50 |  |
| twout | Output Pulse Width | 2.0 | $C x=0$ | $\mathrm{Rx}=5 \mathrm{~K} \Omega$ |  | 540 | 1200 |  | 1500 |  | 1800 | ns |
|  |  | 4.5 |  | $\mathrm{Rx}=1 \mathrm{~K} \Omega$ |  | 180 | 250 |  | 320 |  | 375 |  |
|  |  | 6.0 |  | $\mathrm{Rx}=1 \mathrm{~K} \Omega$ |  | 150 | 200 |  | 260 |  | 320 |  |
|  |  | 2.0 | $\begin{gathered} \mathrm{Cx}=0.01 \mu \mathrm{~F} \\ \mathrm{Rx}=10 \mathrm{~K} \Omega \end{gathered}$ |  | 70 | 83 | 96 | 70 | 96 | 70 | 96 | $\mu \mathrm{s}$ |
|  |  | 4.5 |  |  | 69 | 77 | 85 | 69 | 85 | 69 | 85 |  |
|  |  | 6.0 |  |  | 69 | 77 | 85 | 69 | 85 | 69 | 85 |  |
|  |  | 2.0 | $\begin{aligned} & \mathrm{Cx}=0.1 \mu \mathrm{~F} \\ & \mathrm{Rx}=10 \mathrm{~K} \Omega \end{aligned}$ |  | 0.67 | 0.75 | 0.83 | 0.67 | 0.83 | 0.67 | 0.9 | ms |
|  |  | 4.5 |  |  | 0.67 | 0.73 | 0.77 | 0.67 | 0.77 | 0.67 | 0.8 |  |
|  |  | 6.0 |  |  | 0.67 | 0.73 | 0.77 | 0.67 | 0.77 | 0.67 | 0.8 |  |
| $\Delta t_{\text {WOUT }}$ | Output Pulse Width Error Between Circuits in Same Package |  |  |  |  | $\pm 1$ |  |  |  |  |  | \% |
| ${ }^{t}{ }_{W}(\mathrm{H})$ <br> ${ }^{t} W(L)$ | Minimum Pulse Width ( $\mathrm{A}, \overline{\mathrm{B}}$ ) | 2.0 |  |  |  | 30 | 75 |  | 95 |  | 110 | ns |
|  |  | 4.5 |  |  |  | 8 | 15 |  | 19 |  | 22 |  |
|  |  | 6.0 |  |  |  | 7 | 13 |  | 16 |  | 19 |  |
| ${ }^{\text {w }}$ (L) | Minimum Pulse Width (CD) | 2.0 |  |  |  | 30 | 75 |  | 95 |  | 110 | ns |
|  |  | 4.5 |  |  |  | 8 | 15 |  | 19 |  | 22 |  |
|  |  | 6.0 |  |  |  | 7 | 13 |  | 16 |  | 19 |  |
| $\mathrm{t}_{\text {REM }}$ | Minimum Clear Removal Time | 2.0 |  |  |  | 0 | 15 |  | 15 |  | 20 | ns |
|  |  | 4.5 |  |  |  | 0 | 5 |  | 5 |  | 7 |  |
|  |  | 6.0 |  |  |  | 0 | 5 |  | 5 |  |  |  |
| $\mathrm{t}_{\mathrm{rr}}$ | Minimum Retrigger Time | 2.0 | $\begin{gathered} \mathrm{Cx}=0.1 \mu \mathrm{~F} \\ \mathrm{Rx}=1 \mathrm{~K} \Omega \end{gathered}$ |  |  | 380 |  |  |  |  |  | ns |
|  |  | 4.5 |  |  |  | 92 |  |  |  |  |  |  |
|  |  | 6.0 |  |  |  | 72 |  |  |  |  |  |  |
|  |  | 2.0 | $\begin{gathered} C x=0.01 \mu \mathrm{~F} \\ \mathrm{Rx}=1 \mathrm{~K} \Omega \end{gathered}$ |  |  | 6 |  |  |  |  |  | $\mu \mathrm{s}$ |
|  |  | 4.5 |  |  |  | 1.4 |  |  |  |  |  |  |
|  |  | 6.0 |  |  |  | 1.2 |  |  |  |  |  |  |

## CAPACITIVE CHARACTERISTICS

| Symbol | Parameter | Test Condition |  | Value |  |  |  |  |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathrm{V}_{\mathrm{Cc}}$ <br> (V) |  | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | -40 to $85^{\circ} \mathrm{C}$ |  | -55 to $125^{\circ} \mathrm{C}$ |  |  |
|  |  |  |  | Min. | Typ. | Max. | Min. | Max. | Min. | Max. |  |
| $\mathrm{C}_{\text {IN }}$ | Input Capacitance | 5.0 |  |  | 5 | 10 |  | 10 |  | 10 | pF |
| $\mathrm{C}_{\text {PD }}$ | Power Dissipation Capacitance (note 1) | 5.0 |  |  | 70 |  |  |  |  |  | pF |

1) $\mathrm{C}_{P D}$ is defined as the value of the IC's internal equivalent capacitance which is calculated from the operating current consumption without load. (Refer to Test Circuit); Average operating current can be obtained by the following equation. $I_{C C(o p r)}=C_{P D} \times V_{C C} \times f_{I N}+I_{C C}$ Duty/100 + Ic/2(per monostable) ( $\mathrm{l}_{\mathrm{cc}}$ : Active Supply current) (Duty : \%)

## TEST CIRCUIT



[^2]SWITCHING CHARACTERISTICS TEST WAVEFORM (f=1MHz; $50 \%$ duty cycle)


## SO-16 MECHANICAL DATA

| DIM. | mm. |  |  | inch |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN. | TYP | MAX. | MIN. | TYP. | MAX. |
| A |  |  | 1.75 |  |  | 0.068 |
| a1 | 0.1 |  | 0.2 | 0.003 |  | 0.007 |
| a2 |  |  | 1.65 |  |  | 0.064 |
| b | 0.35 |  | 0.46 | 0.013 |  | 0.018 |
| b1 | 0.19 |  | 0.25 | 0.007 |  | 0.010 |
| C |  | 0.5 |  |  | 0.019 |  |
| c1 | $45^{\circ}$ (typ.) |  |  |  |  |  |
| D | 9.8 |  | 10 | 0.385 |  | 0.393 |
| E | 5.8 |  | 6.2 | 0.228 |  | 0.244 |
| e |  | 1.27 |  |  | 0.050 |  |
| e3 |  | 8.89 |  |  | 0.350 |  |
| F | 3.8 |  | 4.0 | 0.149 |  | 0.157 |
| G | 4.6 |  | 5.3 | 0.181 |  | 0.208 |
| L | 0.5 |  | 1.27 | 0.019 |  | 0.050 |
| M |  |  | 0.62 |  |  | 0.024 |
| S | $8^{\circ}$ (max.) |  |  |  |  |  |



TSSOP16 MECHANICAL DATA

| DIM. | mm. |  |  | inch |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN. | TYP | MAX. | MIN. | TYP. | MAX. |
| A |  |  | 1.2 |  |  | 0.047 |
| A1 | 0.05 |  | 0.15 | 0.002 | 0.004 | 0.006 |
| A2 | 0.8 | 1 | 1.05 | 0.031 | 0.039 | 0.041 |
| b | 0.19 |  | 0.30 | 0.007 |  | 0.012 |
| c | 0.09 |  | 0.20 | 0.004 |  | 0.0089 |
| D | 4.9 | 5 | 5.1 | 0.193 | 0.197 | 0.201 |
| E | 6.2 | 6.4 | 6.6 | 0.244 | 0.252 | 0.260 |
| E1 | 4.3 | 4.4 | 4.48 | 0.169 | 0.173 | 0.176 |
| e |  | 0.65 BSC |  |  | 0.0256 BSC |  |
| K | $0^{\circ}$ |  | $8 \circ$ | $0{ }^{\circ}$ |  | 8 |
| L | 0.45 | 0.60 | 0.75 | 0.018 | 0.024 | 0.030 |



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[^0]:    (1) Cx, Rx, Dx are external components
    (2) Dx is a clamping diode.

    The external capacitor is charged to Vcc in the stand-by-state, i.e. no trigger. When the supply voltage is turned off Cx is discharged mainly trough an internal parasitic diode(see figures). If Cx is sufficiently large and Vcc decreases rapidly, there will be some possibility of damaging the I.C. with a surge current or latch-up. If the voltage supply filter capacitor is large enough and Vcc decrease slowly, the surge current is automatically limited and damage to the I.C. is avoided. The maximum forward current of the parasitic diode is approximately 20 mA . In cases where Cx is large the time taken for the supply voltage to fall to 0.4 Vcc can be calculated as follows :
    $\mathrm{t}_{\mathrm{f}} \geq(\mathrm{Vcc}-0.7) \times \mathrm{Cx} / 20 \mathrm{~mA}$
    In cases where $\mathrm{t}_{\mathrm{f}}$ is too short an external clamping diode is required to protect the I.C. from the surge current.

[^1]:    Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied
    (*) 500 mW at $65{ }^{\circ} \mathrm{C}$; derate to 300 mW by $10 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ from $65^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$

[^2]:    $C_{L}=50 p F$ or equivalent (includes jig and probe capacitance)
    $R_{T}=Z_{\text {OUT }}$ of pulse generator (typically $50 \Omega$ )

